

# Relational reasoning using concurrent separation logic

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# Why prove relational properties of programs?

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`implementation`  $\approx_{ctx}$  `specification`

- ▶ Optimized versions of data structures

`hash_table`  $\approx_{ctx}$  `assoc_list`

- ▶ Proving program transformations

$\forall e_{source}. \text{compile}(e_{source}) \approx_{ctx} e_{source}$

## Language features that complicate refinements

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- ▶ Concurrency

$$\left( x \leftarrow 10; x \leftarrow 11 \right) \not\sim_{ctx} \left( x \leftarrow 11 \right)$$

What do such relational properties mean mathematically?



## Contextual refinement

**Contextual refinement:** the “gold standard” of program refinement:

$$e_1 \lesssim_{\text{ctx}} e_2 : \tau \triangleq \forall (C : \tau \rightarrow \mathbf{N}). \forall v. C[e_1] \downarrow v \implies C[e_2] \downarrow v$$

“Any behavior of a (well-typed) client  $C$  using  $e_1$  can be matched by a behavior of the same client using  $e_2$ ”

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“Any behavior of a (well-typed) client  $C$  using  $e_1$  can be matched by a behavior of the same client using  $e_2$ ”

**Very hard to prove:** Quantification over all clients

## Logical relations to the rescue!

Do not prove contextual refinement directly, but use a **binary logical relation**:

$$e_1 \lesssim e_2 : \tau$$

- ▶  $e_1 \lesssim e_2 : \tau$  is defined structurally on the type  $\tau$
- ▶ Does not involve quantification over all clients  $\mathcal{C}$
- ▶ Soundness  $e_1 \lesssim e_2 : \tau \implies e_1 \lesssim_{\text{ctx}} e_2 : \tau$  proved once and for all

## A bit of history

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Solve circularities by stratifying everything by a natural number corresponding to the number of computation steps

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We tried to take this one step further

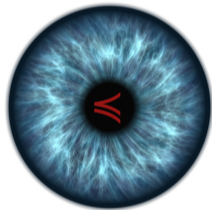


# Prove program refinements using inference rules à la concurrent separation logic

Instead of Hoare triples  $\{P\} e \{Q\}$  we have refinement judgments  $e_1 \preceq e_2 : \tau$

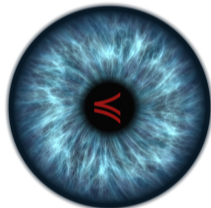
- ▶ Refinement proofs by symbolic execution as we know from separation logic
- ▶ Modular and conditional specifications
- ▶ Modeled using the “logical approach”

**ReLoC**: mechanized separation logic for interactive refinement proofs of fine-grained concurrent programs.



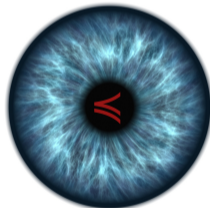
**ReLoC**: mechanized separation logic for interactive refinement proofs of **fine-grained concurrent programs**.

- ▶ **Fine-grained concurrency**: programs use low-level synchronization primitives for more granular parallelism



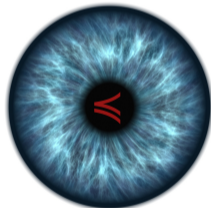
**ReLoC:** **mechanized** separation logic for interactive refinement proofs of fine-grained concurrent programs.

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- ▶ **Fine-grained concurrency**: programs use low-level synchronization primitives for more granular parallelism
- ▶ **Mechanized**: soundness proven sound using the Iris framework in Coq
- ▶ **Interactive refinement proofs**: using high-level tactics in Coq



## ReLoC: (simplified) grammar

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$$P, Q \in \text{Prop} ::= \forall x. P \mid \exists x. P \mid P \vee Q \mid \dots$$
$$\mid P * Q \mid P \multimap Q \mid \ell \mapsto_i v \mid \ell \mapsto_s v$$

### Separation logic for handling mutable state

- ▶  $\ell \mapsto_i v$  for the left-hand side (implementation)
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### Logic with first-class refinement propositions to allow conditional refinements

- ▶  $(\ell_1 \mapsto_i v) \multimap (e_1 \lesssim e_2 : \tau)$
- ▶  $(e_1 \lesssim e_2 : \mathbf{1} \rightarrow \tau) \multimap (f(e_1) \lesssim e_2(); e_2() : \tau)$



# Proving refinements of pure programs

## Some rules for pure programs

### Symbolic execution rules

$$\frac{\Delta \models K[e'_1] \lesssim e_2 : \tau \quad e_1 \rightarrow_{\text{pure}} e'_1}{\Delta \models K[e_1] \lesssim e_2 : \tau}^*$$

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## Some rules for pure programs

### Structural rules

$$\frac{\Delta \Vdash e_1 \lesssim e_2 : \tau \quad * \quad \Delta \Vdash e'_1 \lesssim e'_2 : \tau'}{\Delta \Vdash (e_1, e'_1) \lesssim (e_2, e'_2) : \tau \times \tau'}^*$$

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$$\frac{\exists(R : Val \times Val \rightarrow Prop). \quad [\alpha := R], \Delta \Vdash e_1 \lesssim e_2 : \tau}{\Delta \Vdash \text{pack}(e_1) \lesssim \text{pack}(e_2) : \exists \alpha. \tau}^*$$

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$$\frac{[\tau]_{\Delta}(v_1, v_2)}{\Delta \Vdash v_1 \simeq v_2 : \tau}^* \quad \frac{\square \left( \forall v_1 v_2. [\tau]_{\Delta}(v_1, v_2) \rightarrow \Delta \Vdash e_1[v_1/x_1] \simeq e_2[v_2/x_2] : \sigma \right)}{\Delta \Vdash \lambda x_1. e_1 \simeq \lambda x_2. e_2 : \tau \rightarrow \sigma}^*$$

## Example

**A bit interface:**

$$\text{bitT} \triangleq \exists \alpha. \alpha \times (\alpha \rightarrow \alpha) \times (\alpha \rightarrow \mathbf{2})$$

- ▶ constructor
- ▶ flip the bit
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**Two implementations:**

$$\text{bit\_bool} \triangleq \text{pack}(\text{true}, (\lambda b. \neg b), (\lambda b. b))$$

$$\text{bit\_nat} \triangleq \text{pack}(1, (\lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } 0), (\lambda n. n = 1))$$



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**Refinement (and vice versa):**

$$\text{bit\_bool} \preceq \text{bit\_nat} : \text{bitT}$$

## Proof of the refinement

`pack`(`true`, ( $\lambda b. \neg b$ ), ( $\lambda b. b$ ))

$\approx$

`pack`(`1`, ( $\lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } 0$ ), ( $\lambda n. n = 1$ ))

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where  $R \triangleq \{(\mathbf{true}, 1), (\mathbf{false}, 0)\}$

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$\alpha \times (\alpha \rightarrow \alpha) \times (\alpha \rightarrow \mathbf{2})$

Use structural rule for products

## Proof of the refinement

$[\alpha := R] \models$       where  $R \triangleq \{(\text{true}, 1), (\text{false}, 0)\}$

$\text{true} \lesssim 1$       :  $\alpha$

$(\lambda b. \neg b) \lesssim (\lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } 0)$       :  $\alpha \rightarrow \alpha$

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$\text{true} \rightsquigarrow 1$       :  $\alpha$       (by def of  $R$ )

$(\lambda b. \neg b) \rightsquigarrow (\lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } 0)$       :  $\alpha \rightarrow \alpha$       ( $\lambda$ -rule + symb. exec.)

$(\lambda b. b) \rightsquigarrow (\lambda n. n = 1)$       :  $\alpha \rightarrow \mathbf{2}$

After using the  $\lambda$  rule and case analysis on  $R$ :

$\neg \text{true} \rightsquigarrow \text{if } 1 = 0 \text{ then } 1 \text{ else } 0$       :  $\alpha$

$\neg \text{false} \rightsquigarrow \text{if } 0 = 0 \text{ then } 1 \text{ else } 0$       :  $\alpha$

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$[\alpha := R] \models$       where  $R \triangleq \{(\text{true}, 1), (\text{false}, 0)\}$

$\text{true} \simeq 1$       :  $\alpha$       (by def of  $R$ )

$(\lambda b. \neg b) \simeq (\lambda n. \text{if } n = 0 \text{ then } 1 \text{ else } 0)$       :  $\alpha \rightarrow \alpha$       ( $\lambda$ -rule + symb. exec.)

$(\lambda b. b) \simeq (\lambda n. n = 1)$       :  $\alpha \rightarrow \mathbf{2}$       ( $\lambda$ -rule + symb. exec.)

□

Reasoning about mutable state

**Separation logic to the rescue!**

## “Vanilla” separation logic [O’Hearn, Reynolds, Yang; CSL’01]

**Propositions**  $P, Q$  denote ownership of resources


**Points-to connective**  $\ell \mapsto v$ :

Exclusive ownership of location  $\ell$  with value  $v$

**Separating conjunction**  $P * Q$ :

The resources consists of separate parts satisfying  $P$  and  $Q$

**Basic example:**

$$\{\ell_1 \mapsto v_1 * \ell_2 \mapsto v_2\} \text{swap}(\ell_1, \ell_2) \{\ell_1 \mapsto v_2 * \ell_2 \mapsto v_1\}$$


the  $*$  ensures that  $\ell_1$  and  $\ell_2$  are different memory locations

# Mutable state and separation logic for refinements

There are two versions of the **points-to connective**:

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**Example:**

$$\ell_1 \mapsto_i 4 \quad -* \quad \ell_2 \mapsto_s 0 \quad -* \quad (!\ell_1) \lesssim (\ell_2 \leftarrow 4; !\ell_2) : \mathbf{N}$$



## Some rules for mutable state

### Symbolic execution

$$\frac{l_1 \mapsto_i - \quad * \quad (l_1 \mapsto_i v_1 \quad * \quad \Delta \models K[()] \lesssim e_2 : \tau)}{\Delta \models K[l_1 \leftarrow v_1] \lesssim e_2 : \tau}^*$$

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$$\frac{\forall l_1. l_1 \mapsto_i v_1 \quad * \quad \Delta \Vdash K[l_1] \lesssim e_2 : \tau}{\Delta \Vdash K[\text{ref}(v_1)] \lesssim e_2 : \tau}^* \quad \frac{\forall l_2. l_2 \mapsto_s v_2 \quad * \quad \Delta \Vdash e \lesssim K[l_2] : \tau}{\Delta \Vdash e_1 \lesssim K[\text{ref}(v_2)] : \tau}^*$$

# Reasoning about higher-order functions and concurrency

## State encapsulation

Modules with **encapsulated state**:

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The reference can only be used in the closure

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**Simple example:**

`counter`  $\triangleq$   $(\lambda(). \text{let } x = \text{ref}(1) \text{ in } (\lambda(). \text{FAA}(x, 1))) : \mathbf{1} \rightarrow (\mathbf{1} \rightarrow \mathbf{N})$

- ▶ `counter()` constructs an instance  $c : \mathbf{1} \rightarrow \mathbf{N}$  of the counter module
- ▶ Calling `c()` in subsequently gives  $0, 1, 2, \dots$
- ▶ The reference  $x$  is private to the module

## The problem

Modules with **encapsulated state**:

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We need to guarantee that closures do not get access to exclusive resources

# Persistent resources

The “persistent” modality  $\Box$  in Iris/ReLoC:

$\Box P \triangleq$  “ $P$  holds **without** assuming exclusive resources”

## Examples:

- ▶ Equality is persistent:  $(x = y) \vdash \Box(x = y)$
- ▶ Points-to connectives are not:  $((\ell \mapsto v) \not\vdash \Box(\ell \mapsto v))$
- ▶ More examples later. . .

## ReLoC's $\lambda$ -rule again

The  $\square$  modality makes sure no exclusive resources can escape into closures:

$$\frac{\square \left( \begin{array}{c} \forall v_1 v_2. \llbracket \tau \rrbracket_{\Delta}(v_1, v_2) \multimap * \\ \Delta \Vdash e_1[v_1/x_1] \lesssim e_2[v_2/x_2] : \sigma \end{array} \right)}{\Delta \Vdash \lambda x_1. e_1 \lesssim \lambda x_2. e_2 : \tau \rightarrow \sigma}^*$$

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Prohibits “wrong” refinements, for example:

$$\left( \lambda(). 1 \right) \not\lesssim_{ctx} \left( \text{let } x = \text{ref}(0) \text{ in } (\lambda(). x \leftarrow (1 + !x); !x) \right)$$

Due to  $\square$ , the resource  $x \mapsto_s 0$  cannot be used to prove the closure

But it should be possible to use resources in closures

**For example:**

$$\left( \lambda(). \text{let } x = \text{ref}(1) \text{ in } (\lambda(). \text{FAA}(x, 1)) \right)$$
$$\approx$$
$$\left( \begin{array}{l} \lambda(). \text{let } x = \text{ref}(1), l = \text{newlock } () \text{ in} \\ \quad \lambda(). \text{acquire}(l); \\ \quad \quad \text{let } v = !x \text{ in} \\ \quad \quad x \leftarrow v + 1; \\ \quad \quad \text{release}(l); v \end{array} \right)$$

## Iris-style Invariants

**The invariant connective**  $\boxed{R}$

expresses that  $R$  is maintained as an invariant on the state

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expresses that  $R$  is maintained as an invariant on the state

**Invariants allow to share resources:**

- ▶ A resource  $R$  can be turned into  $\boxed{R}$  at any time
- ▶ Invariants are persistent:  $\boxed{R} \vdash \Box \boxed{R}$
- ▶ ... thus can be used to prove closures



# Iris-style Invariants

## The invariant connective $\boxed{R}$

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### Invariants allow to share resources:

- ▶ A resource  $R$  can be turned into  $\boxed{R}$  at any time
- ▶ Invariants are persistent:  $\boxed{R} \vdash \Box \boxed{R}$
- ▶ ... thus can be used to prove closures

### But that comes with a cost:

- ▶ Invariants  $\boxed{R}$  can only be accessed during atomic steps on the left-hand side
- ▶ ... while multiple steps on the right-hand side can be performed

## Example

```
let x = ref(1) in (λ(). FAA(x, 1))
```

$\rightsquigarrow$

```
let x = ref(1) , l = newlock () in  
  (λ(). acquire(l);  
    let v = !x in  
    x ← v + 1;  
    release(l); v)
```

## Example

```
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## Example

---

$x_1 \mapsto_i 1$

$(\lambda(). \text{FAA}(x_1, 1))$

$\rightsquigarrow$

```
let x = ref(1) , l = newlock () in
  (\lambda(). acquire(l);
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## Example

---

$x_1 \mapsto_i 1$

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$\approx$

```
let x = ref(1), l = newlock () in
  (\lambda(). acquire(l);
    let v = !x in
      x ← v + 1;
      release(l); v)
```

## Example

---

$x_1 \mapsto_i 1$

$x_2 \mapsto_s 1$

$(\lambda(). \text{FAA}(x_1, 1))$

$\rightsquigarrow$

```
let l = newlock () in
(\lambda(). acquire(l);
  let v = !x2 in
  x2 ← v + 1;
  release(l); v)
```

## Example

---

$x_1 \mapsto_i 1$

$x_2 \mapsto_s 1$

$(\lambda(). \text{FAA}(x_1, 1))$

$\rightsquigarrow$

```
let l = newlock () in
  (\lambda(). acquire(l);
    let v = !x2 in
      x2 ← v + 1;
      release(l); v)
```

## Example

---

$x_1 \mapsto_i 1$

$x_2 \mapsto_s 1$

`isLock(l, unlocked)`

$(\lambda(). \text{FAA}(x_1, 1))$

$\rightsquigarrow$

$(\lambda(). \text{acquire}(l);$

`let  $v = !x_2$  in`

$x_2 \leftarrow v + 1;$

`release(l);  $v$ )`



## Example

---

$\exists n.$

$x_1 \mapsto_i n$

$x_2 \mapsto_s n$

`isLock( $l$ , unlocked)`

`( $\lambda().$  FAA( $x_1$ , 1))`

$\approx$

`( $\lambda().$  acquire( $l$ );`

`let  $v = !x_2$  in`

`$x_2 \leftarrow v + 1$ ;`

`release( $l$ );  $v$ )`

## Example

$\exists n. x_1 \mapsto_i n *$
$x_2 \mapsto_s n *$
<code>isLock(<i>l</i>, unlocked)</code>

---

$(\lambda(). \text{FAA}(x_1, 1))$

$\rightsquigarrow$

```
( $\lambda().$  acquire(l);  
  let  $v = !x_2$  in  
   $x_2 \leftarrow v + 1$ ;  
  release(l);  $v$ )
```

## Example

$\exists n. x_1 \mapsto_i n *$ $x_2 \mapsto_s n *$ $\text{isLock}(l, \text{unlocked})$
--

---

$\text{FAA}(x_1, 1)$

$\sim$

$\text{acquire}(l);$

$\text{let } v = !x_2 \text{ in}$

$x_2 \leftarrow v + 1;$

$\text{release}(l); v$

## Example

$\exists n. x_1 \mapsto_i n *$ $x_2 \mapsto_s n *$ $\text{isLock}(l, \text{unlocked})$
--

---

$\text{FAA}(x_1, 1)$

$\approx$

```
acquire(l);  
let v = !x_2 in  
x_2 ← v + 1;  
release(l); v
```

## Example

```
∃n. x1 ↦i n *  
    x2 ↦s n *  
    isLock(l, unlocked)
```

---

```
x1 ↦i n  
x2 ↦s n  
isLock(l, unlocked)
```

```
FAA(x1, 1)
```

≈

```
acquire(l);  
let v = !x2 in  
x2 ← v + 1;  
release(l); v
```

## Example

```
∃n. x1 ↦i n *  
    x2 ↦s n *  
    isLock(l, unlocked)
```

---

x<sub>1</sub> ↦<sub>i</sub> n + 1

x<sub>2</sub> ↦<sub>s</sub> n

isLock(l, unlocked)

n

↗

acquire(l);

let v = !x<sub>2</sub> in

x<sub>2</sub> ← v + 1;

release(l); v

## Example

```
∃n. x1 ↦i n *  
    x2 ↦s n *  
    isLock(l, unlocked)
```

---

x<sub>1</sub> ↦<sub>i</sub> n + 1

x<sub>2</sub> ↦<sub>s</sub> n

isLock(l, unlocked)

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let v = !x<sub>2</sub> in

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## Example

```
∃n. x1 ↦i n *  
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    isLock(l, unlocked)
```

---

x<sub>1</sub> ↦<sub>i</sub> n + 1

x<sub>2</sub> ↦<sub>s</sub> n

isLock(l, locked)

n

↗

let v = !x<sub>2</sub> in

x<sub>2</sub> ← v + 1;

release(l); v



## Example

```
∃n. x1 ↦i n *  
    x2 ↦s n *  
    isLock(l, unlocked)
```

---

x<sub>1</sub> ↦<sub>i</sub> n + 1

x<sub>2</sub> ↦<sub>s</sub> n

isLock(l, locked)

n

↗

let v = !x<sub>2</sub> in

x<sub>2</sub> ← v + 1;

release(l); v

## Example

$\exists n. x_1 \mapsto_i n *$   
 $x_2 \mapsto_s n *$   
 $\text{isLock}(l, \text{unlocked})$

---

$x_1 \mapsto_i n + 1$

$x_2 \mapsto_s n$

$\text{isLock}(l, \text{locked})$

$n$

$\surd$

$x_2 \leftarrow n + 1;$

$\text{release}(l); n$

## Example

$\exists n. x_1 \mapsto_i n *$   
 $x_2 \mapsto_s n *$   
 $\text{isLock}(l, \text{unlocked})$

---

$x_1 \mapsto_i n + 1$

$x_2 \mapsto_s n$

$\text{isLock}(l, \text{locked})$

$n$

$\simeq$

$x_2 \leftarrow n + 1;$

$\text{release}(l); n$

## Example

$$\begin{array}{l} \exists n. x_1 \mapsto_i n * \\ \quad x_2 \mapsto_s n * \\ \quad \text{isLock}(l, \text{unlocked}) \end{array}$$

---

$$x_1 \mapsto_i n + 1$$
$$x_2 \mapsto_s n + 1$$
$$\text{isLock}(l, \text{locked})$$
$$n$$
$$\surd$$
$$\text{release}(l); n$$

## Example

$$\begin{array}{l} \exists n. x_1 \mapsto_i n * \\ \quad x_2 \mapsto_s n * \\ \quad \text{isLock}(l, \text{unlocked}) \end{array}$$

---

$$x_1 \mapsto_i n + 1$$
$$x_2 \mapsto_s n + 1$$
$$\text{isLock}(l, \text{locked})$$
$$n$$
$$\sim$$
$$\text{release}(l); n$$

## Example

$\exists n. x_1 \mapsto_i n *$   
 $x_2 \mapsto_s n *$   
 $\text{isLock}(l, \text{unlocked})$

---

$x_1 \mapsto_i n + 1$

$x_2 \mapsto_s n + 1$

$\text{isLock}(l, \text{unlocked})$

$n$

$\surd$

$n$

## Example

$\exists n. x_1 \mapsto_i n *$   
 $x_2 \mapsto_s n *$   
 $\text{isLock}(l, \text{unlocked})$

---

$n$

$\gamma_2$

$n$

## Wrapping up...

- ▶ ReLoC provides rules allowing this kind of simulation reasoning, formally
- ▶ The example can be done in Coq in almost the same fashion
- ▶ The approach scales to: lock-free concurrent data structures, generative ADTs, examples from the logical relations literature



# Logically atomic relational specifications

## Problem

- ▶ The example that we have seen is a bit more subtle: the fetch-and-add (**FAA**) function is not a physically atomic instruction
- ▶ What kind of specification can we give to **FAA** as a compound program?

# Logically atomic relational specifications

## Problem

- ▶ The example that we have seen is a bit more subtle: the fetch-and-add ([FAA](#)) function is not a physically atomic instruction
- ▶ What kind of specification can we give to [FAA](#) as a compound program?

## Our solution

Relational version of TaDA-style logically atomic triples in ReLoC

# Implementation in Coq

ReLoC is build on top of the **Iris framework**, so we can inherit:

- ▶ Iris's Invariants
- ▶ Iris's ghost state
- ▶ Iris's Coq infrastructure
- ▶ ...



# The proofs we have done in Coq

ReLoC judgments  $e_1 \lesssim e_2 : \tau$  are modeled as a shallow embedding using the “logical approach” to logical relations

## Proved in Coq:

- ▶ Proof rules: All the ReLoC rules hold in the shallow embedding
- ▶ Soundness:  $e_1 \lesssim e_2 : \tau \implies e_1 \lesssim_{ctx} e_2 : \tau$
- ▶ Actual program refinements: concurrent data structures, and examples from the logical relations literature

Need to reason in separation logic!

## Iris Proof Mode (IPM) [Krebbers *et al.*; POPL'17]

**Lemma** test  $\{A\}$  (P Q : iProp) ( $\Psi : A \rightarrow \text{iProp}$ ) :  
P \* ( $\exists a, \Psi a$ ) \* Q  $\multimap$  Q \*  $\exists a, P * \Psi a$ .

**Proof.**

```
iIntros "[H1 [H2 H3]]".  
iDestruct "H2" as (x) "H2".  
iSplitL "H3".  
- iAssumption.  
- iExists x.  
  iFrame.
```

**Qed.**

## Iris Proof Mode (IPM) [Krebbers et al.; POPL'17]

**Lemma** test {A} (P Q : iProp) ( $\Psi : A \rightarrow \text{iProp}$ ) :  
P \* ( $\exists a, \Psi a$ ) \* Q  $\text{--}^*$  Q \*  $\exists a, P * \Psi a$ .

**Proof.**

iInt **Lemma in the Iris logic**  
iDes...  
iSplitL "H3".  
- iAssumption.  
- iExists x.  
iFrame.

**Qed.**



# Iris Proof Mode (IPM) [Krebbers et al.; POPL'17]

**Lemma** test {A} (P Q : iProp) ( $\Psi : A \rightarrow \text{iProp}$ ) :  
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iSplitL "H3".  
- iAssumption.  
- iExists x.  
  iFrame.
```

**Qed.**

1 subgoal

A : Type

P, Q : iProp

$\Psi : A \rightarrow \text{iProp}$

x : A

----- (1/1)

"H1" : P

"H2" :  $\Psi x$

"H3" : Q

-----\*

Q \* ( $\exists a : A, P * \Psi a$ )

# Iris Proof Mode (IPM) [Krebbers et al.; POPL'17]

```
Lemma test {A} (P Q : iProp) ( $\Psi : A \rightarrow iProp$ ) :  
  P * ( $\exists a, \Psi a$ ) * Q  $\multimap$  Q *  $\exists a, P * \Psi a$ .
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Proof.

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iIntros "[H1 [H2 H3]]".  
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\* means: resources should be split

# Iris Proof Mode (IPM) [Krebbers et al.; POPL'17]

```
Lemma test {A} (P Q : iProp) ( $\Psi : A \rightarrow iProp$ ) :  
  P * ( $\exists a, \Psi a$ ) * Q  $\dashv$ * Q *  $\exists a, P * \Psi a$ .
```

Proof.

```
iIntros "[H1 [H2 H3]]".  
iDestruct "H2" as (x) "H2".  
iSplitL "H3".  
- iAssumption.
```

The hypotheses for the left conjunct

Qed.

1 subgoal

A : Type

P, Q : iProp

$\Psi : A \rightarrow iProp$

x : A

----- (1/1)

"H1" : P

"H2" :  $\Psi x$

"H3" : Q

----- \*

Q \* ( $\exists a : A, P * \Psi a$ )

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# Iris Proof Mode (IPM) [Krebbers et al.; POPL'17]

```
Lemma test {A} (P Q : iProp) ( $\Psi : A \rightarrow iProp$ ) :  
  P * ( $\exists a, \Psi a$ ) * Q  $\multimap$  Q *  $\exists a, P * \Psi a$ .
```

Proof.

```
iIntros "[H1 [H2 H3]]".  
iDestruct "H2" as (x) "H2".  
iSplitL "H3".  
- iAssumption.
```

The hypotheses for the left conjunct

Qed.

2 subgoals

A : Type

P, Q : iProp

$\Psi : A \rightarrow iProp$

x : A

-----(1/2)  
"H3" : Q

-----\*

Q

----- (2/2)

"H1" : P

"H2" :  $\Psi x$

-----\*

$\exists a : A, P * \Psi a$

## Iris Proof Mode (IPM) [Krebbers et al.; POPL'17]

**Lemma** test  $\{A\}$  (P Q : iProp) ( $\Psi : A \rightarrow \text{iProp}$ ) :  
P \* ( $\exists a, \Psi a$ ) \* Q  $\multimap$  Q \*  $\exists a, P * \Psi a$ .

**Proof.**

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iIntros "[H1 [H2 H3]]".  
iDestruct "H2" as (x) "H2".  
iSplitL "H3".  
- iAssumption.  
- iExists x.  
  iFrame.
```

**Qed.**

## Iris Proof Mode (IPM) [Krebbers et al.; POPL'17]

```
Lemma test {A} (P Q : iProp) ( $\Psi : A \rightarrow iProp$ ) :  
  P * ( $\exists a, \Psi a$ ) * Q -* Q *  $\exists a, P * \Psi a$ .
```

Proof.

```
iIntros "[H1 [H2 H3]]".  
by iFrame.
```

Qed.

No more subgoals.

We can also solve this lemma automatically

## ReLoC in Iris Proof Mode

- ▶ The ReLoC rules are just lemmas that can be `iApplied`
- ▶ We have more automated support for symbolic execution
- ▶ Iris Proof Mode features a special context for persistent hypotheses, which is crucial for dealing with invariants

## Persistent propositions in Iris Proof Mode

**Lemma** test {PROP : bi} {A}  
 (P Q : PROP) ( $\Psi : A \rightarrow \text{PROP}$ ) :  
 P \*  $\square (\exists a, \Psi a) \multimap \exists a, \Psi a$  \* (P \*  $\Psi a$ ).

**Proof.**

```
iIntros "[H1 #H2]".  
iDestruct "H2" as (x) "H2".  
iExists x.  
iSplitL "H2".  
- iAssumption.  
- by iFrame.
```

**Qed.**



## Persistent propositions in Iris Proof Mode

**Lemma** test {PROP : bi} {A}  
(P Q : PROP) ( $\Psi : A \rightarrow \text{PROP}$ ) :  
 $P * \Box (\exists a, \Psi a) \multimap \exists a, \Psi a * (P * \Psi a)$ .

**Proof.**

i| **Persistent modality**  
i| ~~exists~~  $\exists a, \Psi a$   
iExists x.  
iSplitL "H2".  
- iAssumption.  
- by iFrame.

**Qed.**

## Persistent propositions in Iris Proof Mode

```
Lemma test {PROP : bi} {A}
  (P Q : PROP) (Ψ : A → PROP) :
  P * □ (∃ a, Ψ a) -* ∃ a, Ψ a * (P * Ψ a).
```

Proof.

```
iIntros "[H1 #H2]".
iDestruct "H2" as (x) "H2".
iExists x.
iSplitL "H2".
- iAssumption.
- by iFrame.
```

Qed.

```
1 subgoal
PROP : bi
A : Type
P, Q : PROP
Ψ : A → PROP
----- (1/1)
"H2" : ∃ a : A, Ψ a
----- □
"H1" : P
----- *
∃ a : A, Ψ a * (P * Ψ a)
```

Moves hypothesis to **persistent** context

# Persistent propositions in Iris Proof Mode

```
Lemma test {PROP : bi} {A}
  (P Q : PROP) (Ψ : A → PROP) :
  P * □ (∃ a, Ψ a) -* ∃ a, Ψ a * (P * Ψ a).
```

Proof.

```
iIntros "[H1 #H2]".
iDestruct "H2" as (x) "H2".
iExists x.
iSplitL "H2".
- iAssumption.
- by iFrame.
```

Qed.

```
1 subgoal
PROP : bi
A : Type
P, Q : PROP
Ψ : A → PROP
x : A
----- (1/1)
"H2" : Ψ x
----- □
"H1" : P
----- *
∃ a : A, Ψ a * (P * Ψ a)
```

# Persistent propositions in Iris Proof Mode

```
Lemma test {PROP : bi} {A}
  (P Q : PROP) (Ψ : A → PROP) :
  P * □ (∃ a, Ψ a) -* ∃ a, Ψ a * (P * Ψ a).
```

Proof.

```
iIntros "[H1 #H2]".
iDestruct "H2" as (x) "H2".
iExists x.
iSplitL "H2".
- iAssumption
```

Qe Do not need to split persistent context

```
1 subgoal
PROP : bi
A : Type
P, Q : PROP
Ψ : A → PROP
x : A
----- (1/1)
"H2" : Ψ x
----- □
"H1" : P
----- *
Ψ x * (P * Ψ x)
```

# Persistent propositions in Iris Proof Mode

```
Lemma test {PROP : bi} {A}
  (P Q : PROP) (Ψ : A → PROP) :
  P * □ (∃ a, Ψ a) -* ∃ a, Ψ a * (P * Ψ a).
```

Proof.

```
iIntros "[H1 #H2]".
iDestruct "H2" as (x) "H2".
iExists x.
iSplitL "H2".
- iAssumption.
- by iFrame.
```

Qed.

2 subgoals

PROP : bi

A : Type

P, Q : PROP

Ψ : A → PROP

x : A

----- (1/2)

"H2" : Ψ x

----- □

Ψ x

----- (2/2)

"H2" : Ψ x

----- □

"H1" : P

----- \*

P \* Ψ x

# Conclusions

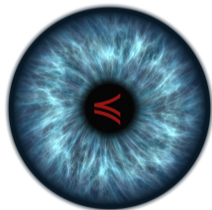
# Conclusions and future work

## Contributions

- ▶ ReLoC: a logic that allows to carry out refinement proofs interactively in Coq
- ▶ New approach to modular refinement specifications for logically atomic programs
- ▶ Case studies: concurrent data structures, and examples from the logical relations literature

## Future work

- ▶ Program transformations
- ▶ Refinements between programs in different language
- ▶ Other relational properties of concurrent programs



## ReLoC: A Mechanised Relational Logic for Fine-Grained Concurrency

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### Abstract

We present ReLoC: a logic for proving refinements of programs in a language with higher-order state, fine-grained concurrency, polymorphism and recursive types. The core of our logic is a judgement  $e \lesssim e' : \tau$ , which expresses that a program  $e$  refines a program  $e'$  at type  $\tau$ . In contrast to earlier work on refinements for languages with higher-order state and concurrency, ReLoC provides type- and structure-directed rules for manipulating this judgement, whereas previously, such proofs were carried out by unfolding the judgement into its definition in the model. These more abstract proof rules make it simpler to carry out refinement proofs.

Moreover, we introduce *logically atomic relational specifications*: a novel approach for relational specifications for compound expressions that take effect at a single instant in time. We demonstrate how to formalise and prove such relational specifications in ReLoC,

```
read  $\triangleq \lambda x (). !x$   
incs  $\triangleq \lambda x l. \text{acquire } l; \text{let } n = !x \text{ in } x \leftarrow 1 + n; \text{release } l; n$   
counters  $\triangleq \text{let } l = \text{newlock } () \text{ in let } x = \text{ref}(0) \text{ in}$   
    (read  $x, \lambda(). \text{inc}_s x l$ )  
inci  $\triangleq \text{rec } \text{inc } x = \text{let } c = !x \text{ in}$   
    if CAS( $x, c, 1 + c$ ) then  $c$  else  $\text{inc } x$   
counteri  $\triangleq \text{let } x = \text{ref}(0) \text{ in (read } x, \lambda(). \text{inc}_i x)$ 
```

**Figure 1.** Two concurrent counter implementations.

are often referred to as the gold standards of equivalence and refine-



Thank you!

Download ReLoC at <https://cs.ru.nl/~dfrumin/reloc/>

Download Iris at <https://iris-project.org/>

**Advertisement.** I currently have a vacancy for a fully funded PhD position (4 years) in the beautiful Netherlands

**Topics:** Separation logic for multilingual programs, asynchronous I/O, non-functional properties, verified compilation, proof automation, tactics, ...

**Interested/Know someone? Get in touch!**

