

# A Separation Logic for Non-determinism and Sequence Points in C Formalized in Coq

Robbert Krebbers

Radboud University Nijmegen

May 14, 2014 @ TYPES, Paris, France

## What is this program supposed to do?

```
int main() {  
    int x;  
    int y = (x = 3) + (x = 4);  
    printf("%d %d\n", x, y);  
}
```

Let us try some compilers

- ▶ Clang prints 4 7, seems just left-right
- ▶ GCC prints 4 8, **does not correspond to any evaluation order**

This program violates the **sequence point** restriction

- ▶ due to two unsequenced writes to x
- ▶ resulting in **undefined behavior**
- ▶ thus both compilers are right

# Undefined behavior in C

“Garbage in, garbage out” principle

- ▶ Programs with **undefined behavior** are not statically excluded
- ▶ Undefined behavior  $\Rightarrow$  all bets are off
- ▶ Allows compilers to omit (expensive) dynamic checks

**A compiler independent C semantics should account for undefined behavior**

## Examples

- ▶ **Sequenced** side-effects are allowed

```
(x = f()) ? (x = x + 1) : 0;
```

- ▶ Side-effects are useful in a while, for, return, ...

```
while ((x = getchar()) != EOF)
    /* do something */
```

- ▶ Non-determinism is subtle in innocent looking examples:

```
*p = g (x, y, z);
```

Here, g may change p, so the evaluation order matters


- ▶ Interleaving of subexpressions is possible, for example

```
printf("a") + (printf("b") + printf("c"));
```

may print "bac"

# Contribution

A **compiler independent** small step operational, and axiomatic, semantics for non-determinism and sequence points, supporting:

- ▶ expressions with function calls, assignments, conditionals
- ▶ undefined behavior due to integer overflow
- ▶ parametrized by integer types
- ▶ dynamically allocated memory (`malloc` and `free`)
- ▶ non-local control (`return` and `goto`)
- ▶ local variables (and pointers to those)
- ▶ mutual recursion
- ▶ **separation logic**
- ▶ **soundness proof fully checked by  Coq**

## Key idea

**Observation:** non-determinism corresponds to concurrency

**Idea:** use the separation logic rule for parallel composition

$$\frac{\{P_1\} e_1 \{Q_1\} \quad \{P_2\} e_2 \{Q_2\}}{\{P_1 * P_2\} e_1 \odot e_2 \{Q_1 * Q_2\}}$$

What does this mean:

- ▶ Split the memory into two disjoint parts
- ▶ Prove that  $e_1$  and  $e_2$  can be executed safely in their part
- ▶ Now  $e_1 \odot e_2$  can be executed safely in the whole memory

Disjointness  $\Rightarrow$  no sequence point violation

## Definition of the memory

Given a set of permissions  $P$ , we define:

$$m \in \text{mem} := \text{index} \rightarrow_{\text{fin}} (\text{val} \times P)$$

$$b \in \text{index} := \mathbb{N}$$

$$v \in \text{val} ::= \text{indet} \mid \text{int}_T n \mid \text{ptr } b \mid \text{NULL}$$

Integer types: unsigned char, signed int, ...

## C permissions

The C permissions contain:

- ▶ Locked flag to catch sequence point violations
  - ▶ Assignment: lock memory location
  - ▶ Sequence point: unlock memory locations
- ▶ A fraction  $(0, 1]_{\mathbb{Q}}$  for share accounting of read only memory
- ▶ Block scope variable or allocated with `malloc` flag

A **permission system**  $P$  abstracts from these details.

- ▶  $\cup : P \rightarrow P \rightarrow P$  and  $\perp : P \rightarrow P \rightarrow \text{Prop}$
- ▶ **kind** :  $P \rightarrow \{\text{Free, Write, Read, Locked}\}$
- ▶ **lock, unlock** :  $P \rightarrow P$
- ▶ satisfying certain axioms

We lift these operations to memories  $\text{index} \rightarrow_{\text{fin}} (\text{val} \times P)$



# The language

## Our language

$\odot \in \text{binop} ::= == \mid <= \mid + \mid - \mid * \mid / \mid \% \mid \dots$

$e \in \text{expr} ::= x_i \mid [v]_{\Omega} \mid e_1 := e_2 \mid f(\vec{e}) \mid \text{load } e \mid \text{alloc}$   
 $\mid \text{free } e \mid e_1 \odot e_2 \mid e_1 ? e_2 : e_3 \mid (\tau) e$

$s \in \text{stmt} ::= e \mid \text{skip} \mid \text{goto } l \mid \text{return } e \mid \text{block } c \ s \mid s_1 ; s_2$   
 $\mid l : s \mid \text{while}(e) \ s \mid \text{if } (e) \ s_1 \ \text{else } s_2$

Values  $[v]_{\Omega}$  carry a set  $\Omega$  of indexes (memory locations) to be unlocked at the next sequence point

# Operational semantics

**Head reduction for expressions**  $(e, m) \rightarrow_h (e', m')$  (9 rules)

- ▶ On assignments: locked index  $b$  added to  $\Omega_1 \cup \Omega_2$   
 $([\text{ptr } b]_{\Omega_1} := [v]_{\Omega_2}, m) \rightarrow_h ([v]_{\{b\} \cup \Omega_1 \cup \Omega_2}, \text{lock } b (m[b := v]))$
- ▶ On sequence points:  $\Omega$  unlocked in memory  
 $([v]_{\Omega} ? e_2 : e_3, m) \rightarrow_h (e_2, \text{unlock } \Omega m)$  provided ...

Gives a local treatment of sequence points

**Small step reduction**  $\mathbf{S}(k, \phi, m) \rightarrow \mathbf{S}(k', \phi', m')$  (33 rules)

- ▶  $(k, \phi)$  gives the position in the *whole* program
- ▶ Uses evaluation contexts to lift head reduction
- ▶ Different  $\phi$ s for expressions, statements, function calls

# Assertions of separation logic

Defined using a **shallow embedding**:

$$P, Q \in \text{assert} := \text{stack} \rightarrow \text{mem} \rightarrow \text{Prop}$$

↑  
Maps variables to indexes in memory

Some assertions:

$$(P * Q) \rho m := \exists m_1 m_2 .$$

$$m = m_1 \cup m_2 \wedge m_1 \perp m_2 \wedge P \rho m_1 \wedge Q \rho m_2$$

$$(e_1 \overset{\gamma}{\mapsto} e_2) \rho m := \exists b v . \llbracket e_1 \rrbracket_{\rho, m} = \text{ptr } b \wedge$$

$$\llbracket e_2 \rrbracket_{\rho, m} = v \wedge m = \{(b, (v, \gamma))\}$$

$$(P \triangleright) \rho m := P \rho (\text{unlock } (\text{locks } m) m)$$

(with  $e_1$  and  $e_2$  side-effect free)

# The Hoare “triples”

**Statement judgment**  $\Delta; J; R \vdash \{P\} s \{Q\}$

Function conditions

Goto/return conditions

$Q : \text{assert}$

**Expression judgment**  $\Delta \vdash \{P\} e \{Q\}$

$Q : \text{val} \rightarrow \text{assert}$

In the semantics: if  $P$  holds beforehand, then

- ▶  $e$  does not crash
- ▶  $Q \vee v$  holds afterwards when terminating with  $v$
- ▶ with framing memories that can change at each step

# The axiomatic semantics

## 24 separation logic proof rules, e.g.:

For assignments:

$$\frac{\text{Write } \subseteq \text{ kind } \gamma \quad \{P_1\} e_1 \{Q_1\} \quad \{P_2\} e_2 \{Q_2\} \quad \forall a v. ((Q_1 a * Q_2 v) \rightarrow ((a \xrightarrow{\gamma} -) * R a v))}{\{P_1 * P_2\} e_1 := e_2 \{\lambda v. \exists a. (a \xrightarrow{\text{lock } \gamma} v) * R a v\}}$$

For dereferencing:

$$\frac{\text{kind } \gamma \neq \text{Locked} \quad \{P\} e \{\lambda a. \exists v. Q a v * (a \xrightarrow{\gamma} v)\}}{\{P\} \text{load } e \{\lambda v. \exists a. Q a v * (a \xrightarrow{\gamma} v)\}}$$

For the conditional:

$$\frac{\{P\} e_1 \{\lambda v. v \neq \text{indet} \wedge P' v \triangleright\} \quad \{\exists v. \text{istrue } v \wedge P' v\} e_2 \{Q\} \quad \dots}{\{P\} e_1 ? e_2 : e_3 \{Q\}}$$

Common separation logic and more complex rules can be derived

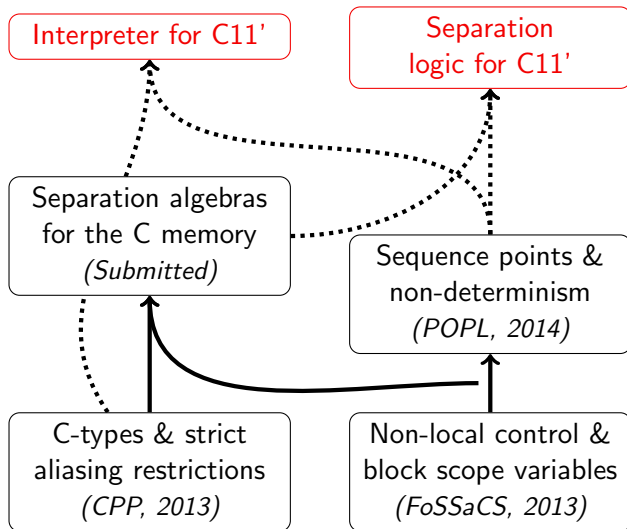
# Formalization in Coq

- ▶ Extremely useful for debugging
- ▶ Notations close to those on paper
- ▶ Various extensions of the separation logic
- ▶ Uses lots of automation
- ▶ 10 000 lines of code



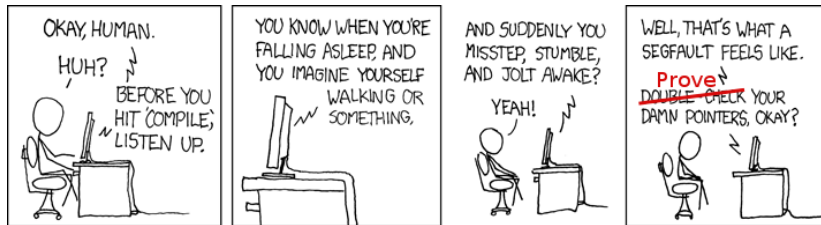
```
Lemma ax_load  $\Delta$  A  $\gamma$  e P Q :  
  perm_kind  $\gamma \neq$  Locked  $\rightarrow$   
   $\Delta \setminus A \models_e \{ \{ P \} \} e \{ \{ \lambda a, \exists v, Q a v * \text{valc } a \mapsto \{ \gamma \} \text{ valc } v \} \} \rightarrow$   
   $\Delta \setminus A \models_e \{ \{ P \} \} \text{load } e \{ \{ \lambda v, \exists a, Q a v * \text{valc } a \mapsto \{ \gamma \} \text{ valc } v \} \}.$ 
```

## The bigger picture / Future work



# Questions

Sources: <http://robertkrebbers.nl/research/ch2o/>



(<http://xkcd.com/371/>)